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### **Collision detection (part 2): box intersection | 0**

we discussed collision detection in general and surveyed some This was a big problem in the 1970's and early 1980's in VLSI B. Chazelle, (1988) A

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time- and VLSI-optimal, algorithm for convex hull computation on meshes with multiple broadcas IL (1993) III, 196-201. [9] B. Chazelle,

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Approximation Schemes for Partitioning: Convex VLSI, Robotics, Graphics Bernard Chazelle and David P. Dobkin. Optimal convex decompositions.

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A VLSI Network for Variable Size FFT's. B. Chazelle: Pages: 697-707: Although the problem of the construction of optimal k-processor schedules for unit time

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the largest empty rectangle problem for the case of points within rectangle an optimal algorithm of time complexity is  $\Theta(n \log n)$  A. Naamad, D. T. Lee and W

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